

**Rules:** All answers should be as developed as possible. Some questions are more guided or open than others; for the latter, there can be more than one admissible answer, the thorough treatment of the question will be privileged over one particular answer. If you think you need to add an extra assumption, say it explicitly in your answer. Duration: 3 hours.

In the whole exam, unless explicitly specified, we let  $(\Omega, \mathcal{A})$  be a measurable space. We denote by  $\mathcal{P}(\Omega)$  the set of probability distributions over  $\Omega$ , and we let  $\mu$  and  $\nu$  be two probability measures on  $(\Omega, \mathcal{A})$ . In addition, we assume that  $\tau$  is a  $\sigma$ -finite measure on  $(\Omega, \mathcal{A})$  satisfying  $\mu \ll \tau$  and  $\nu \ll \tau$  and define  $p = d\mu/d\tau, q = d\nu/d\tau$ .

**Exercise 1.** — The *Hellinger distance* between  $\mu$  and  $\nu$  is defined as follows:

$$H(\mu, \nu) := \sqrt{\int (\sqrt{p} - \sqrt{q})^2 d\tau} = \sqrt{\int (\sqrt{d\mu} - \sqrt{d\nu})^2}. \quad (1)$$

Show the following properties:

1.  $H(\mu, \nu) \geq 0$  with equality if and only if  $\mu = \nu$ .
2.  $H$  is symmetric and verifies the triangle inequality.
3.  $H^2(\mu, \nu) = 2 \left(1 - \int \sqrt{pq} d\tau\right) = 2 \left(1 - \int \sqrt{d\mu d\nu}\right)$ .
4.  $\frac{1}{2} H^2(\mu, \nu) \leq \|\mu - \nu\|_{TV}$ . *Hint: we recall that  $\|\mu - \nu\|_{TV} = 1 - \int \min(p, q) d\tau$ .*
5.  $\|\mu - \nu\|_{TV} \leq H(\mu, \nu) \sqrt{1 - \frac{H^2(\mu, \nu)}{4}}$ . *Hint: we can first show that  $\int \min(p, q) d\tau + \int \max(p, q) d\tau = 2$*

**Exercise 2** (IPM on quadratics). — In this exercise, we restrict ourselves to distributions on  $\mathbb{R}$ . Let us consider the following Integral Probability Metric (IPM) candidate:

$$d(\mu, \nu) := \sup_{f \in \mathcal{F}_q} \left| \int f d\mu - \int f d\nu \right|$$

where the function class  $\mathcal{F}_q := \{x \mapsto ax^2 + bx + c : a, b, c \in [-1, 1]^3\}$  is a set of quadratic functions on  $\mathbb{R}$ .

1. Can we get rid of the absolute value in the definition of  $d$ ?
2. How can you express  $d$  using the moments of  $\mu$  and  $\nu$ ?  
(We recall that the  $k$ -th moment of  $\mu$  is  $m_k(\mu) = \mathbb{E}_{X \sim \mu}[X^k]$ ,  $k \in \mathbb{N}$ )
3. Is  $d$  a metric on probability measures on  $\mathbb{R}$ ?
4. Is  $d$  a metric on Gaussian distributions? More generally, for what families of distributions is  $d$  a metric?
5. Can we compare  $d$  with  $W_1$ ? With the total variation? What if we restricted ourselves to probability measures on  $[0, 1]$ ? *Hint: we recall that  $W_1$  and the total variation are IPMs with  $\mathcal{F}$  the set of 1-Lipchitz continuous functions and the set of functions with  $\infty$ -norm bounded by 1 respectively.*
6. Is the condition  $\{a, b, c \in [-1, 1]^3\}$  in  $\mathcal{F}_q$  necessary to define a metric? If not, by what can we replace it?

**Exercise 3** (Nash Equilibria). — The parts of this exercise are independent.

A— *2x2 Coordination Game.* Consider the following two-player game in normal form. Both players have two strategies:  $A$  and  $B$ . The payoff matrix is given by:

	$A$	$B$
$A$	(3, 3)	(0, 2)
$B$	(2, 0)	(1, 1)

1. Identify all *pure strategy* Nash equilibria.
  2. Find the *mixed strategy* Nash equilibrium and verify that in equilibrium each player is strongly indifferent among the pure strategies played with positive probability.
- B– *Iterated Elimination of Strictly Dominated Strategies in a 3×3 Game.* Consider the following game with Player 1 choosing among rows  $T$ ,  $M$ , and  $B$ , and Player 2 choosing among columns  $L$ ,  $C$ , and  $R$ :

	$L$	$C$	$R$
$T$	(2, 0)	(1, 1)	(4, 2)
$M$	(3, 4)	(1, 2)	(2, 3)
$B$	(1, 3)	(0, 2)	(3, 0)

3. Identify a strategy for Player 1 that is strictly dominated and eliminate it.
4. Then, for the reduced game, identify a strictly dominated strategy for Player 2 and eliminate it.
5. Find the pure strategy Nash equilibria in the resulting 2×2 game.
6. Find the mixed Nash equilibrium of the full 3×3 game.

**Exercise 4.** — Let  $X_1, \dots, X_n$  be i.i.d. samples from distribution  $\mu$  on  $\mathbb{R}$  and define the empirical measure

$$\mu_n = \frac{1}{n} \sum_{i=1}^n \delta_{X_i}.$$

We give ourselves a family  $(q_\lambda)_{\lambda \in \Lambda}$  of probability distributions on  $\mathbb{R}$  parametrized by  $\lambda \in \Lambda \subset \mathbb{R}$  (eg. the family of exponential distributions). The goal of the exercise is to explore different ways of tuning  $\lambda$  and their consequences in terms of variational inference.

1. Show that

$$\text{KL}(\mu||q_\lambda) = \mathbb{E}_{X \sim \mu}[-\log(q_\lambda(X))] + C \quad (2)$$

where  $C$  is a quantity independent from  $\lambda$  to precise. *Hint: we recall that  $\text{KL}(\mu||\nu) = \int \log\left(\frac{d\mu}{d\nu}\right) d\mu$  if  $\mu \ll \nu$  and  $+\infty$  otherwise.*

2. Deduce that with probability one,

$$\arg \min_{\lambda \in \Lambda} \text{KL}(\mu||q_\lambda) = \arg \max_{\lambda \in \Lambda} \lim_{n \rightarrow \infty} \frac{1}{n} \sum_{i=1}^n \log(q_\lambda(X_i)) \quad (3)$$

what is the interpretation of this result?

Now, we note  $g = \log \circ q_\lambda$  and consider the distributionally robust problem

$$\begin{aligned} \sup_{\nu \in \mathcal{P}(\mathbb{R})} \mathbb{E}_\nu[g] &= \int g(x) d\nu(x) \\ \text{s.t. } \text{KL}(\nu||\mu_n) &\leq \rho \end{aligned} \quad (4)$$

where  $\rho \geq 0$  is the robustness radius.

3. If  $\rho = 0$ , what is the closed form expression of problem (4)? What if  $\rho \rightarrow +\infty$ ?
4. For some fixed  $\rho \in [0, +\infty)$ , what is the support of the optimal  $\nu^*$  (that we will assume to exist)? Then, how can problem (4) be reformulated as finite-dimensional optimization problem?
5. Let  $n = 2, \rho = 0.1$ , what is the optimal value of problem (4)? *Hint: we give  $x \log(2x) + (1-x) \log(2(1-x)) = 0.1$  for  $x = 0.28$  and  $x = 0.72$ .*
6. In fact, one can show that the value of problem (4) is equal to  $\inf_{\gamma > 0} \{\gamma\rho + \gamma \log \mathbb{E}_{\mu_n} \exp(g/\gamma)\}$ . How can you relate this to question 3.?
7. Why is the expression of 6. more adapted than equation (4) to study the problem as  $n \rightarrow \infty$ ?

**Exercise 5** (*f*-Divergences). — Let  $\mu, \nu \in \mathcal{P}(\Omega)$  be such that  $\mu \ll \nu$ . Then, for a convex function  $f : X := [0, +\infty) \rightarrow \mathbb{R} \cup \{+\infty\}$  such that  $f(x)$  is finite for all  $x > 0$ ,  $f(1) = 0$ , and  $f(0) = \lim_{t \rightarrow 0^+} f(t)$ , the *f*-divergence of  $\mu$  from  $\nu$  is defined as

$$D_f(\mu \parallel \nu) \equiv \int_{\Omega} f\left(\frac{d\mu}{d\nu}\right) d\nu. \quad (5)$$

Let  $f^*$  be the convex conjugate of  $f$ , ie  $f^*(y) := \sup \{ \langle y, x \rangle - f(x) : x \in X \}$  for all  $y \in \mathbb{R}$ . Let  $\text{effdom}(f^*)$  be the effective domain of  $f^*$ , that is,  $\text{effdom}(f^*) = \{y : f^*(y) < \infty\}$ .

1. Show that

$$\mathbb{E}_{\mu}[g] \leq D_f(\mu \parallel \nu) + \mathbb{E}_{\nu}[f^* \circ g] \quad (6)$$

for all  $g : \Omega \rightarrow \text{effdom}(f^*)$ . (*Hint: you can use that  $f^*(y) + f(x) \geq xy$  for all  $x, y$  by convex conjugation*)

In fact, we have the following variational principle:

$$D_f(\mu \parallel \nu) = \sup_{g : \Omega \rightarrow \text{effdom}(f^*)} \mathbb{E}_{\mu}[g] - \mathbb{E}_{\nu}[f^* \circ g] \quad (7)$$

that we will take as granted for the remainder of the exercise.

2. For  $f(x) = x \log x$ , verify that  $D_f$  is the Kullback-Liebler divergence. What is  $f^*$ ? Instantiate (7) in that case.
3. For  $f(x) = \frac{1}{2}|x - 1|$ , show that  $D_f$  is an integral probability metric. What common distance does this correspond to?

In addition, if  $g : \Omega \rightarrow \text{effdom}(f^*)$  is upper-bounded and  $\lim_{t \rightarrow +\infty} f(t) = +\infty$ , convex duality tells us similarly that:

$$\sup_{\mu \in \mathcal{P}(\Omega) : \mu \ll \nu} \{ \mathbb{E}_{\mu}[g] - D_f(\mu \parallel \nu) \} = \inf_{\lambda \in \mathbb{R}} \{ \mathbb{E}_{\nu}[f^*(g + \lambda)] - \lambda \} \quad (8)$$

that we will also take as granted for the remainder of the exercise.

4. Instantiate (8) with  $f(x) = x \log x$ . What kind of result of the course do we recover?
5. Instantiate (8) with  $f(x) = (x - 1)^2$ . Is  $D_f$  a distance? What are the striking differences with the previous question?
6. Let  $\Omega = \{a_1, a_2, \dots, a_n\}$  be a set of  $n$  points. What is  $\sup_{\mu \in \mathcal{P}(\Omega)} \{ \mathbb{E}_{\mu}[g] \}$ ?
7. In the setup of question 6., instantiate (8) with  $f(x) = x \log x$  and  $\nu$  the uniform distribution over these points. Show that we recover a well-known smoothing of the maximum.
8. For a general  $\Omega$ , how can we use (8) to find an approximation of the supremum of  $g$ ? What do we have to compute?

**Bonus.** Why don't we have simply  $\sup_{\mu \in \mathcal{P}(\Omega) : \mu \ll \nu} \{ \mathbb{E}_{\mu}[g] - D_f(\mu \parallel \nu) \} = \mathbb{E}_{\nu}[f^* \circ g]$ ? Or rather, for which space  $\mathcal{Y}$  do we have  $\sup_{\mu \in \mathcal{Y} : \mu \ll \nu} \{ \mathbb{E}_{\mu}[g] - D_f(\mu \parallel \nu) \} = \mathbb{E}_{\nu}[f^* \circ g]$ ?